

Lesson Plan

Name of the Faculty : Dr. Rajender Kumar Tayal
 Discipline : Mechanical Engineering
 Semester : 5th
 Subject : Theory of Machines (TOM)
 Lesson Plan duration : 17 weeks (01.10.2021 to 28.01.2022)
 Work load per week : Lecture – 03, Practical – 02

Week	Theory	
	Lecture Day	Topic (Including assessment/test)
1 st	1 st	Subject introduction and overview
	2 nd	1 Simple Mechanisms: 1.1 Kinematics of Machines: - Definition of Kinematics, Dynamics, Statics, Kinetics, Kinematic link, Kinematic Pair and its types
	3 rd	1.1 Constrained motion and its types, Kinematic chain and its types
2 nd	4 th	1.1 Mechanism, inversion, machine and structure.
	5 th	1.2 Inversions of Kinematic Chain: Inversion of four bar chain, coupled wheels of Locomotive & Pantograph.
	6 th	1.2 Inversion of Single Slider Crank chain- Rotary I.C. Engines mechanism, Crank and Slotted lever quick return mechanism.
3 rd	7 th	1.2 Inversion of Double Slider Crank Chain- Scotch Yoke Mechanism & Oldham's Coupling.
	8 th	2 Power Transmission: 2.1 Introduction to Belt and Rope drives. 2.2 Types of belt drives.
	9 th	2.3 Concept of velocity ratio, slip and creep; crowning of pulleys (simple numericals)
4 th	10 th	2.4 Flat and V belt drive: Ratio of driving tensions, power transmitted, centrifugal tension, and condition for maximum horse power (simple numericals)
	11 th	2.5 Different types of chains and their terminology
	12 th	2.6 Gear Drive - Simple, compound, reverted and epicyclic gear trains(simple numericals)
5 th	13 th	2.7 Relative advantages and disadvantages of various drives

	14 th	Simple numericals
	15 th	Simple numericals
6 th	16 th	3. Flywheel: 3.1 Principle and applications of flywheel
	17 th	3.2 Turning - moment diagram of flywheel for different engines.
	18 th	3.3 Fluctuation of speed and fluctuation of energy - Concept only.
7 th	19 th	1st sessional test (Tentative)
	20 th	Assessment
	21 st	3.4 Coefficient of fluctuation of speed and coefficient of fluctuation of energy.
8 th	22 nd	Simple numericals
	23 rd	Simple numericals
	24 th	4. Governor: 4.1 Function of a governor, comparison of flywheel and governor.
9 th	25 th	4.2 Simple description and working of Watt and Porter governor
	26 th	4.2 Simple description and working of Hartnel governor
	27 th	4.2 Simple numerical based on watt and porter governor
10 th	28 th	4.2 Simple numerical based on watt and porter governor
	29 th	4.3 Terminology used in governors: Height, equilibrium speed, Hunting, isochronisms
	30 th	Stability, sensitiveness of a governor.
11 th	31 st	2nd sessional test (Tentative)
	32 nd	Assessment
	33 rd	5. Cams: 5.1 Definition and function of cam
12 th	34 th	5.1 Description of different types of cams and followers with simple line diagram.
	35 th	5.2 Terminology of cam profile.
	36 th	5.3 Displacement diagram for uniform velocity.
13 th	37 th	5.3 Displacement diagram for S.H.M.
	38 th	5.3 Displacement diagram for uniform acceleration and deceleration.

	39 th	6. Balancing: 6.1 Need of balancing, Concept of static and dynamic balancing.
14 th	40 th	6.2 Introduction to balancing of rotating masses in the same plane and different Planes (simple numericals)
	41 st	6.2 Introduction to balancing of rotating masses in the same plane and different Planes (simple numericals)
	42 nd	7. Vibrations: 7.1 Causes of vibrations in machines, Their harmful effects and remedies
15 th	43 rd	7.2 Types-longitudinal, transverse and torsional vibrations. 7.3 Damping of vibrations
	44 th	3rd sessional test (Tentative)
	45 th	Assessment
16 th	46 th	Revision
	47 th	Revision
	48 th	Revision
17 th	49 th	Revision
	50 th	Revision
	51 st	Revision